



Professional Packaging Systems

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Fanuc CRX-25iA Cobot Food Grade Collaborative Robot



At a Glance

- Max Payload: 25/30 kg
- Reach: 1889 mm
- Axis: 6
- Mechanical Weight: 135 kg

Pricing

Call us at **888-318-0083**

Many options are available. Complete details will need to be finalized to determine requirements and final system costs. Work with your Pro Pac representative to build this machine to your specifications.

Robot Arm with 25/30 kg Max Payload

The Fanuc CRX-25iA Cobot food-grade collaborative robot is designed for the food and beverage industries. Equipped with NSF-H1 food-grade grease, white epoxy paint, and rust/chemical-resistant plating, the CRX-25iA food-grade cobot is an ideal solution for food handling, wet environments, or strict hygiene requirements.

Pro Pac provides custom end-of-arm tools and configurations that seamlessly integrate with Fanuc robots and the needs of any packaging line.

Specifications

Max Payload: 25/30 kg

Reach: 1889 mm

Axis: 6

Mechanical Weight: 135

Repeatability: ± 0.05 mm

Mounting: Floor, inverted, wall

Please [contact Pro Pac](#) or call 888-318-0083 for your robotic equipment.

Specifications of Fanuc Food Grade CRX Robots

Specification	CRX-5iAFood Grade	CRX- 10iAFood Grade	CRX- 10iA/LFood Grade	CRX- 20iA/LFood Grade	CRX- 30iAFood Grade
Type	5	10	10	20	30
Controlled Axis	6	6	6	6	6
Max Load at Wrist (kg)	5	10	10	20	30/25
Reach (mm) ¹	994	1,249	1,418	1,418	1,756/1,889 ⁴
Repeatability (mm) ³	±0.03	±0.04	±0.04	±0.04	±0.05
Mass (kg)	25	40	40	41	135
Installation Floor Upside Down Wall	Standard	Standard	Standard	Standard	Standard
Motion Range					
J1 Axis Rotation (°)	400	380	360	360	360
J2 Axis Rotation (°)	360	360	360	360	360
J3 Axis Rotation (°)	635	570	540	540	540
J4 Axis Wrist Rotation (°)	380	380	380	380	380
J5 Axis Wrist Swing (°)	360	360	360	360	360
J6 Axis Wrist Rotation (°)	450	450	450	450	450
Max Speed Collaborative Mode (mm/s) ²	1,000	1,000	1,000	1,000	1,000
Max Speed High-Speed Mode (mm/s) ²	2,000	2,000	2,000	2,000	2,000
Allowable Load Moment at Wrist					
J4 Axis (Nm)	19.0	34.8	34.8	70.0	100.0
J5 Axis (Nm)	15.4	26.0	26.0	64.0	74.0
J6 Axis (Nm)	6.7	11.0	11.0	30.0	32.0
Allowable Load Inertia at Wrist					
J4 Axis (kgm ²)	0.77	1.28	1.28	4.00	4.70

J5 Axis (kgm ²)	15.4	26.0	26.0	64.0	74.0
J6 Axis (kgm ²)	0.10	0.30	0.30	2.00	2.00

Installation Environment

Input Power Source (VAC)	100-120200-240	100-120200-240	100-120200-240	100-120200-240	100-120200-240
Ambient Operating Temp (°C)	0-45	0-45	0-45	0-45	0-45

Protection

Body Standard / Optional	IP67	IP67	IP67	IP67	IP67
Wrist & J3 Arm Standard / Optional	IP67	IP67	IP67	IP67	IP67

- 1) Reach specification from faceplate
- 2) Necessary to set a motion speed according to risk assesment of system
- 3) Compliant with ISO9283
- 4) Operating space expanded when 25kg payload mode selected

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